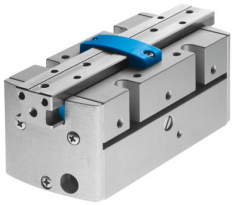
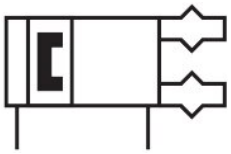
Parallel gripper
HGPP-10-A

Part number: 525658





Data sheet

Feature	Value
Size	10
Stroke per gripper jaw	2 mm
Max. interchangeability	0.1 mm
Max. gripper jaw angular play ax, ay	0 deg
Max. gripper jaw backlash Sz	0 mm
Rotational symmetry	0.05 mm
Pneumatic gripper repetition accuracy	0.02 mm
Number of gripper jaws	2
Actuator system	Pneumatic
Mode of operation	Double-acting
Gripper function	Parallel
Gripping force backup	None
Structural design	Gear rack/pinion
Position sensing	For Hall sensor For inductive sensors
Operating pressure	2 bar...8 bar
Max. operating frequency of pneumatic gripper	4 Hz
Min. opening time at 6 bar	22 ms
Min. closing time at 6 bar	34 ms
Max. mass per external gripper finger	50 g
Operating medium	Compressed air as per ISO 8573-1:2010 [7:4:4]
Information on operating and pilot media	Operation with oil lubrication possible (required for further use)
Corrosion resistance class (CRC)	2 - Moderate corrosion stress
LABS (PWIS) conformity	VDMA24364-B2-L
Ambient temperature	5 °C...60 °C
Gripping force per gripper jaw at 6 bar, opening	80 N 40 N
Gripping force per gripper jaw at 6 bar, closing	80 N 40 N
Mass moment of inertia	0.43 kgcm²
Maximum force on gripper jaw Fz, static	40 N
Maximum torque on gripper jaw, Mx static	1.5 Nm

Feature	Value
Maximum torque on gripper jaw, My static	1.5 Nm
Maximum torque on gripper jaw, Mz static	1.5 Nm
Product weight	126 g
Type of mounting	With internal thread
Pneumatic connection	M3
Note on materials	RoHS compliant
Cover cap material	POM
Housing material	Wrought aluminum alloy, hard-anodized
Gripper jaw material	Wrought aluminum alloy, nickel-plated